

$$i\hbar \frac{\partial}{\partial t} |\Phi(t)\rangle = \hat{H} |\Phi(t)\rangle$$

where  $|\Phi\rangle$  represents the state of the system described by the hamiltonian  $\hat{H}$ .

This has the formal solution  $|\Phi(mt)\rangle = e^{-im\tau\hat{H}} |\Phi(t=0)\rangle$   
where  $m=0,1,2,\dots$  is the number of timesteps  $\tau$ .

► For a charged particle in a static magnetic field

$$\hat{H} = \frac{1}{2m^*} (\underline{P} - e\underline{A})^2 + V$$

where  $m^*$  is the effective mass of the particle with charge  $e$  and:

$\underline{P} = -i\hbar\nabla$  is the momentum operator  
 $V$  and  $\underline{A}$  are the scalar and vector potentials which encapsulate the effect of the electromagnetic field, via

$$\underline{B} = \nabla \times \underline{A}, \quad \underline{E} = -\nabla V - \frac{\partial \underline{A}}{\partial t}$$

2-D  $\Rightarrow$  given  $\underline{A} = [A_x(x,y), 0, 0]$

we have that  $A_x(x,y) = -\int_0^y B(x,y) dy$

★ We will, however, set  $\underline{A} = 0$  in our simplified derivation of the method!

Fixing the unit of length by the wavelength  $\lambda$  and energy in units of  $E = \frac{\hbar^2 k^2}{2m^*}$  ( $k = 2\pi/\lambda$ ) and time in units of  $\hbar/E$ . These dimensionless variables simplify the hamiltonian to:

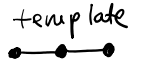
$$\hat{H} = -\frac{1}{4\pi^2} \left[ \left( \frac{\partial}{\partial x} - iA_x(x,y) \right)^2 + \frac{\partial^2}{\partial y^2} \right] + V(x,y)$$

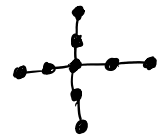
So far this is the same as in [Raedt & Michielson '94] but now we will continue by simplifying a lot!

1. Set  $\underline{B} = 0$ !
2. Discretize the operator  $\nabla^2$  to 2<sup>nd</sup> order on the grid, instead of 4<sup>th</sup> order!
3. Use 2<sup>nd</sup> order in time, instead of 4<sup>th</sup> order!
4. Start developing the method in 1-D.

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$$\nabla^2 u_e = \frac{1}{\Delta^2} (u_{e+1} + u_{e-1} - 2u_e) + \mathcal{O}(\Delta^2)$$



(instead of 2-D 4th order stencil )

$$\text{Now: } H = -\frac{1}{4\pi^2} \frac{\partial^2}{\partial x^2} + V(x)$$

$$H \phi_e(t) = \frac{1}{4\pi^2 \Delta^2} \left\{ -\phi_{e+1}(t) - \phi_{e-1}(t) + (2 + 4\pi^2 \Delta^2 V_e) \phi_e(t) \right\}$$

(compare this to equation 1.9 from the paper)

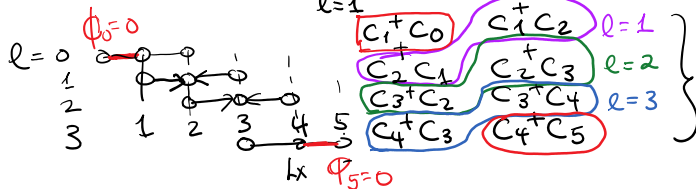
$$|\phi(t)\rangle = \sum_{e=1}^{L_x} \phi_e(t) \underbrace{c_e^\dagger}_{\text{creation operator at grid point } e} |0\rangle$$

state vector

It is far easier to express the formal solution using the creation,  $c_e^\dagger$ , and annihilation,  $c_e$ , operators:

$$|\phi(m\tau)\rangle = e^{-im\tau H} |\phi(t=0)\rangle \quad \text{where}$$

$$H = -\frac{1}{4\pi^2 \Delta^2} \sum_{l=1}^{L_x-1} (c_l^\dagger c_{l+1} + c_{l+1}^\dagger c_l) + \frac{1}{4\pi^2 \Delta^2} \sum_{l=1}^{L_x} (2 + 4\pi^2 \Delta^2 V_l)$$



$L_x = 4$  Note that the fact that the red contributions are missing is an implicit application of the free boundary cond.  $\phi_0 = \phi_5 = 0!$

Each term in the first sum involves an interaction between a pair of lattice sites  $(l, l+1)$ .

The aim now is to express the solution as a product of  $2 \times 2$  matrix operation acting on pairs of lattice sites. Each  $2 \times 2$  matrix op can be computed analytically. We do this calculation now.

Recall  $e^y = 1 + y + \frac{y^2}{2!} + \frac{y^3}{3!} + \frac{y^4}{4!} + \frac{y^5}{5!}$

$y = ix$ , then

$$e^{ix} = 1 + ix - \frac{x^2}{2} - i\frac{x^3}{3!} + \frac{x^4}{4!} + i\frac{x^5}{5!} - \dots$$

$$= \left( 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \right)$$

$$+ i \left( x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} \right)$$

$$= \cos x + i \sin x$$

Now to calculate the exponentials of the fermi operators  $c_e, c_e^\dagger$ :

$$|\phi\rangle = \sum_e \phi_e c_e^\dagger |0\rangle \quad \begin{cases} \{c_e^\dagger, c_{e'}^\dagger\} = 0 \\ \{c_e, c_{e'}\} = 0 \\ \{c_e^\dagger, c_{e'}\} = \delta_{ee'} \end{cases}$$

$$e^{-i\tau(\alpha c_e^\dagger c_{e+1} + \alpha^* c_{e+1}^\dagger c_e)} |\phi\rangle$$

$$= |\phi\rangle - i\tau(\alpha c_e^\dagger c_{e+1} + \alpha^* c_{e+1}^\dagger c_e) |\phi\rangle + \dots$$

$$\text{Let } x = -\tau(\alpha c_e^\dagger c_{e+1} + \alpha^* c_{e+1}^\dagger c_e)$$

$$x|\phi\rangle = -\tau \sum_n \phi_n \alpha c_e^\dagger c_{e+1}^\dagger c_n^\dagger |0\rangle - \tau \sum_n \phi_n \alpha^* c_{e+1}^\dagger c_e c_n^\dagger |0\rangle$$

Trick to move  $c_e$  so it acts on  $|0\rangle$ :

$$= \delta_{e+1, n} - \underbrace{c_n^\dagger c_{e+1}}_{\langle 0| = 0!} = \delta_{en} - \underbrace{c_n^\dagger c_e}_{\langle 0| = 0!}$$

$$x|\phi\rangle = -\tau \alpha \phi_{e+1} c_e^\dagger |0\rangle - \tau \alpha^* \phi_e c_{e+1}^\dagger |0\rangle$$

$$x^2|\phi\rangle = x(x|\phi\rangle) = +\tau^2 \alpha^2 c_e^\dagger c_{e+1}^\dagger \phi_{e+1} c_e^\dagger |0\rangle + \tau^2 |\alpha|^2 c_e^\dagger c_{e+1}^\dagger \phi_e c_{e+1}^\dagger |0\rangle \\ + \tau^2 |\alpha|^2 c_{e+1}^\dagger c_e \phi_{e+1} c_e^\dagger |0\rangle + \tau^2 \alpha^{*2} c_{e+1}^\dagger c_e \phi_e c_{e+1}^\dagger |0\rangle$$

$$= \tau^2 \alpha^2 c_e^\dagger \phi_{e+1} (\delta_{e+1, e+1} - c_e^\dagger c_{e+1}) |0\rangle$$

$$+ \tau^2 |\alpha|^2 c_e^\dagger \phi_e (\delta_{e+1, e+1} - c_{e+1}^\dagger c_{e+1}) |0\rangle$$

$$+ \tau^2 |\alpha|^2 c_{e+1}^\dagger \phi_{e+1} (\delta_{ee} - c_e^\dagger c_e) |0\rangle$$

$$+ \tau^2 \alpha^{*2} c_{e+1}^\dagger \phi_e (\delta_{e, e+1} - c_{e+1}^\dagger c_e) |0\rangle$$

$$x^2|\phi\rangle = \tau^2 |\alpha|^2 (\phi_e c_e^\dagger + \phi_{e+1} c_{e+1}^\dagger) |0\rangle$$

$$x^3|\phi\rangle = x(x^2|\phi\rangle)$$

$$= -\tau^3 \alpha |\alpha|^2 (c_e^\dagger c_{e+1}^\dagger \phi_e c_e^\dagger + c_e^\dagger c_{e+1}^\dagger \phi_{e+1} c_{e+1}^\dagger) |0\rangle$$

$$- \tau^3 \alpha^* |\alpha|^2 (c_{e+1}^\dagger c_e \phi_e c_e^\dagger + c_{e+1}^\dagger c_e \phi_{e+1} c_{e+1}^\dagger) |0\rangle$$

$$= -\tau^3 \alpha |\alpha|^2 (\phi_e c_e^\dagger (\delta_{e+1, e} - c_e^\dagger c_{e+1}) |0\rangle +$$

$$\phi_{e+1} c_e^\dagger (\delta_{e+1, e+1} - c_{e+1}^\dagger c_{e+1}) |0\rangle)$$

$$- \tau^3 \alpha^* |\alpha|^2 (\phi_e c_{e+1}^\dagger (\delta_{ee} - c_e^\dagger c_e) |0\rangle +$$

$$\phi_{e+1} c_{e+1}^\dagger (\delta_{e, e+1} - c_{e+1}^\dagger c_e) |0\rangle)$$

$$x^3|\phi\rangle = -\tau^3 \alpha |\alpha|^2 \phi_{e+1} c_e^\dagger |0\rangle - \tau^3 \alpha^* |\alpha|^2 \phi_e c_{e+1}^\dagger |0\rangle$$

$$= \tau^2 |\alpha|^2 (x|\phi\rangle) ! \quad \downarrow$$

$$x^4|\phi\rangle = x(x^3|\phi\rangle) = \tau^2 |\alpha|^2 x(x|\phi\rangle) = \tau^2 |\alpha|^2 x^2|\phi\rangle$$

$$= \tau^4 |\alpha|^4 (\phi_e c_e^\dagger + \phi_{e+1} c_{e+1}^\dagger) |0\rangle$$

$$\cos x |\phi\rangle = \left( 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \right) |\phi\rangle$$

For:  $|\phi\rangle = (\phi_e c_e^\dagger + \phi_{e+1} c_{e+1}^\dagger) |0\rangle$  ← state of the pair of lattice sites.

$$\cos x |\phi\rangle = \left( 1 - \frac{1}{2} \tau^2 |\alpha|^2 + \frac{1}{4!} \tau^4 |\alpha|^4 - \dots \right) = \cos(\tau |\alpha|) |\phi\rangle$$

$$\sin x |\phi\rangle = \left( 1 - \frac{\tau^2 |\alpha|^2}{3!} + \frac{\tau^4 |\alpha|^4}{5!} - \dots \right) x |\phi\rangle$$

$$= \left( \tau |\alpha| - \frac{\tau^3 |\alpha|^3}{3!} + \frac{\tau^5 |\alpha|^5}{5!} - \dots \right) \frac{1}{\tau |\alpha|} x |\phi\rangle$$

$$\begin{aligned}
\sin x |\Phi\rangle &= \left(1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots\right) \times |\Phi\rangle \\
&= \left(\tau|\alpha| - \frac{\tau^3|\alpha|^3}{3!} + \frac{\tau^5|\alpha|^5}{5!} - \dots\right) \frac{1}{\tau|\alpha|} \times |\Phi\rangle \\
&= \sin(\tau|\alpha|) \frac{1}{\tau|\alpha|} \times |\Phi\rangle \\
&= \sin(\tau|\alpha|) \left(-\frac{\alpha}{|\alpha|} \Phi_{e\pm} c_e^\dagger |0\rangle - \frac{\alpha^*}{|\alpha|} \Phi_e c_{e\pm}^\dagger |0\rangle\right) \\
\left(-\frac{\alpha}{|\alpha|} c_e^\dagger c_{e\pm} - \frac{\alpha^*}{|\alpha|} c_{e\pm}^\dagger c_e\right) |\Phi\rangle &= -\frac{\alpha}{|\alpha|} c_e^\dagger c_{e\pm} \Phi_e c_e^\dagger |0\rangle \\
&\quad - \frac{\alpha}{|\alpha|} c_e^\dagger c_{e\pm} \Phi_{e\pm} c_{e\pm}^\dagger |0\rangle \\
&\quad - \frac{\alpha^*}{|\alpha|} c_{e\pm}^\dagger c_e \Phi_e c_e^\dagger |0\rangle \\
&\quad - \frac{\alpha^*}{|\alpha|} c_{e\pm}^\dagger c_e \Phi_{e\pm} c_{e\pm}^\dagger |0\rangle \\
&= -\frac{\alpha}{|\alpha|} \Phi_{e\pm} c_e^\dagger |0\rangle - \frac{\alpha^*}{|\alpha|} \Phi_e c_{e\pm}^\dagger |0\rangle
\end{aligned}$$

So  $\sin x |\Phi\rangle = \left(-\frac{\alpha}{|\alpha|} c_e^\dagger c_{e\pm} - \frac{\alpha^*}{|\alpha|} c_{e\pm}^\dagger c_e\right) \sin(\tau|\alpha|) |\Phi\rangle$

For  $|\Phi\rangle = \Phi_e c_e^\dagger |0\rangle + \Phi_{e\pm} c_{e\pm}^\dagger |0\rangle$  we have that:

$$\begin{aligned}
e^{-i\tau(\alpha c_e^\dagger c_{e\pm} + \alpha^* c_{e\pm}^\dagger c_e)} |\Phi\rangle &= \\
\left[\cos(\tau|\alpha|) - i\left(\frac{\alpha}{|\alpha|} c_e^\dagger c_{e\pm} + \frac{\alpha^*}{|\alpha|} c_{e\pm}^\dagger c_e\right) \sin(\tau|\alpha|)\right] |\Phi\rangle
\end{aligned}$$

$$\begin{aligned}
c_e^\dagger c_{e\pm} (c_{e\pm}^\dagger |0\rangle) &= c_e^\dagger |0\rangle \Rightarrow \Phi_{e\pm} \rightarrow \Phi_e' \\
c_e^\dagger c_{e\pm} (c_e^\dagger |0\rangle) &= 0 \\
c_{e\pm}^\dagger c_e (c_{e\pm}^\dagger |0\rangle) &= 0 \\
c_{e\pm}^\dagger c_e (c_e^\dagger |0\rangle) &= c_{e\pm}^\dagger |0\rangle \Rightarrow \Phi_e \rightarrow \Phi_{e\pm}'
\end{aligned}$$

↑ new states  
↓

Using matrix notation  $|\Phi\rangle = \begin{pmatrix} \Phi_e \\ \Phi_{e\pm} \end{pmatrix}$  this operation results in the following:

$$\begin{pmatrix} \cos(\tau|\alpha|) & -i\frac{\alpha}{|\alpha|} \sin(\tau|\alpha|) \\ -i\frac{\alpha^*}{|\alpha|} \sin(\tau|\alpha|) & \cos(\tau|\alpha|) \end{pmatrix} \begin{pmatrix} \Phi_e \\ \Phi_{e\pm} \end{pmatrix} = \begin{pmatrix} \Phi_e' \\ \Phi_{e\pm}' \end{pmatrix}$$

Note:  $\frac{\alpha}{|\alpha|} = \frac{\alpha|\alpha|}{|\alpha|^2} = \frac{\alpha|\alpha|}{\alpha\alpha^*} = \alpha^{*-1}|\alpha|$ ,  $\frac{\alpha^*}{|\alpha|} = \alpha^{-1}|\alpha|$

$$M = \begin{pmatrix} \cos(\tau|\alpha|) & -i\alpha^{*-1}|\alpha|\sin(\tau|\alpha|) \\ -i\alpha^{-1}|\alpha|\sin(\tau|\alpha|) & \cos(\tau|\alpha|) \end{pmatrix}$$

$$\begin{pmatrix} \phi_e' \\ \phi_{e+1}' \end{pmatrix} = M \begin{pmatrix} \phi_e \\ \phi_{e+1} \end{pmatrix}$$