

# MICROSCOPE mission

## A test of the Equivalence principle in space



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on behalf of MICROSCOPE team

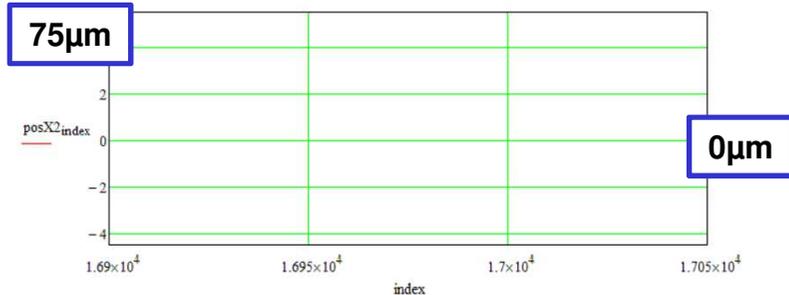


# Launched on the 25<sup>th</sup> of April 2016

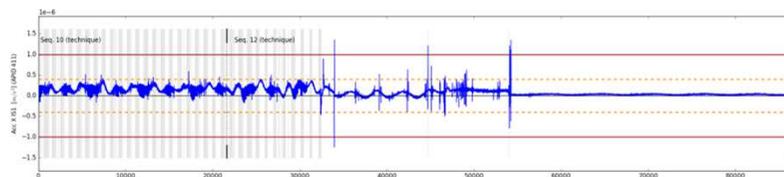


- 25<sup>th</sup> of April 2016: satellite launch as piggy bag of Sentinel 1B by Soyuz

SUEP – titanium TM acquisition along X

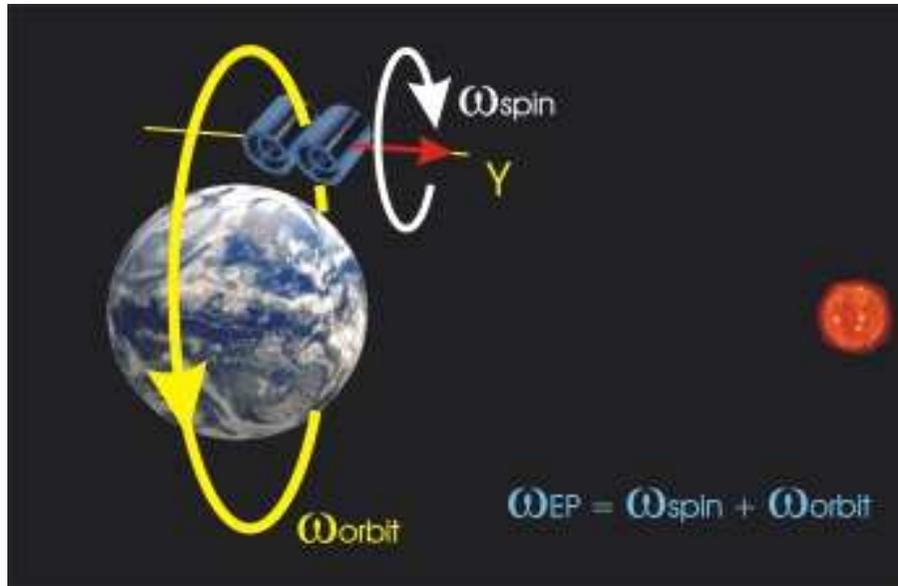


- 2<sup>nd</sup> of May 2016 : test-masses release and electrostatic control in robust mode
- 11<sup>th</sup> May : 1<sup>st</sup> test of Payload science mode



- 7<sup>th</sup> of June 2016: 1<sup>st</sup> Attitude control with hybridization of the Star Sensor & the Payload angular accelerometer
- 9<sup>th</sup> of June 2016 : 1<sup>st</sup> “drag-free” above 6 axes on Earth’s low orbit

# Principle of the test in space



- Comparison of the measured accelerations ( $a_1$  &  $a_2$ ) applied on a pair of test-masses when orbiting on the same orbit in the Earth's gravity field ( $7,92\text{m/s}^2$  @  $717\text{km}$ )
- 2 test bodies in Pt(Rh10%) for systematic error evaluation
- 2 test bodies in Pt(Rh10%) vs Ti(Al6%) for the EP test
- The measurement axis, X, is in the orbital plane = cylinder axis

$$\eta = \frac{a_1 - a_2}{\frac{1}{2}(a_1 + a_2)} = \frac{\left(\frac{mg}{mi}\right)_1 - \left(\frac{mg}{mi}\right)_2}{\frac{1}{2}\left[\left(\frac{mg}{mi}\right)_1 + \left(\frac{mg}{mi}\right)_2\right]}$$

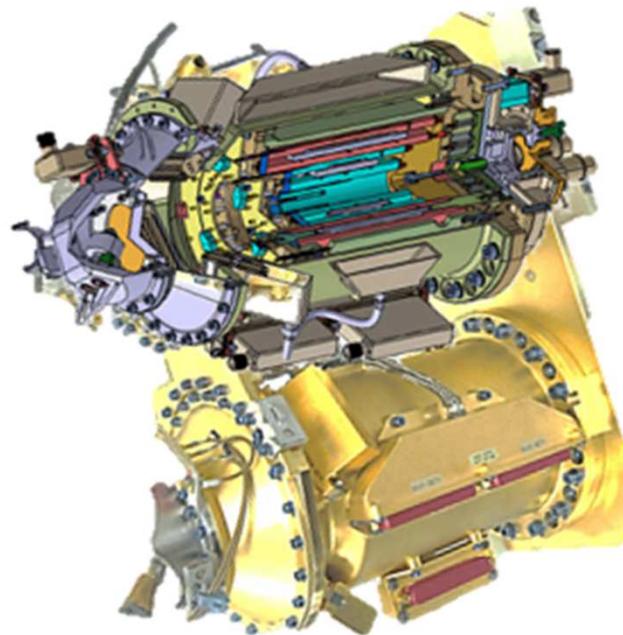
evaluated @  $10^{-15}$  level

The eventual violation signal frequency is at orbital frequency + s/c rotation rate (spin mode)

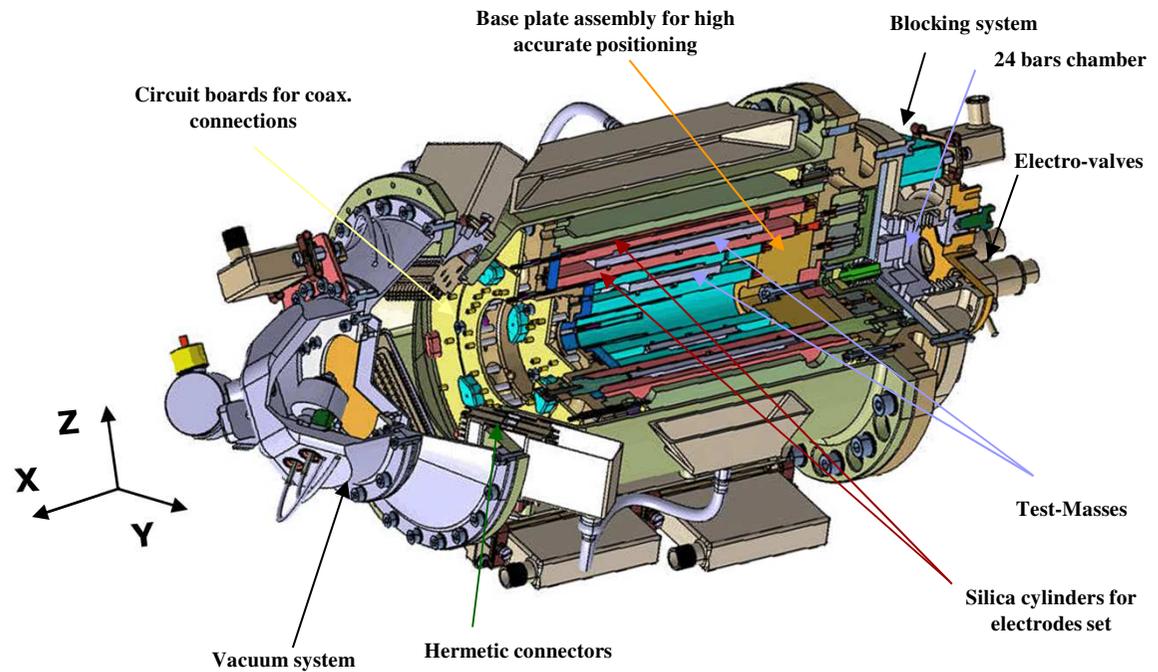
# The instrument



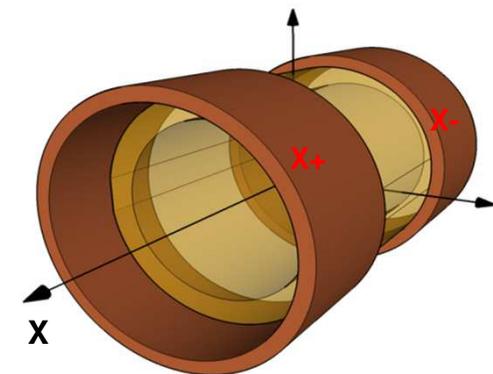
**ICU : digital control laws, data conditioning**



**SU: 2 Sensor units REF + EP**



**FEEU : 2 low noise Electronics units**

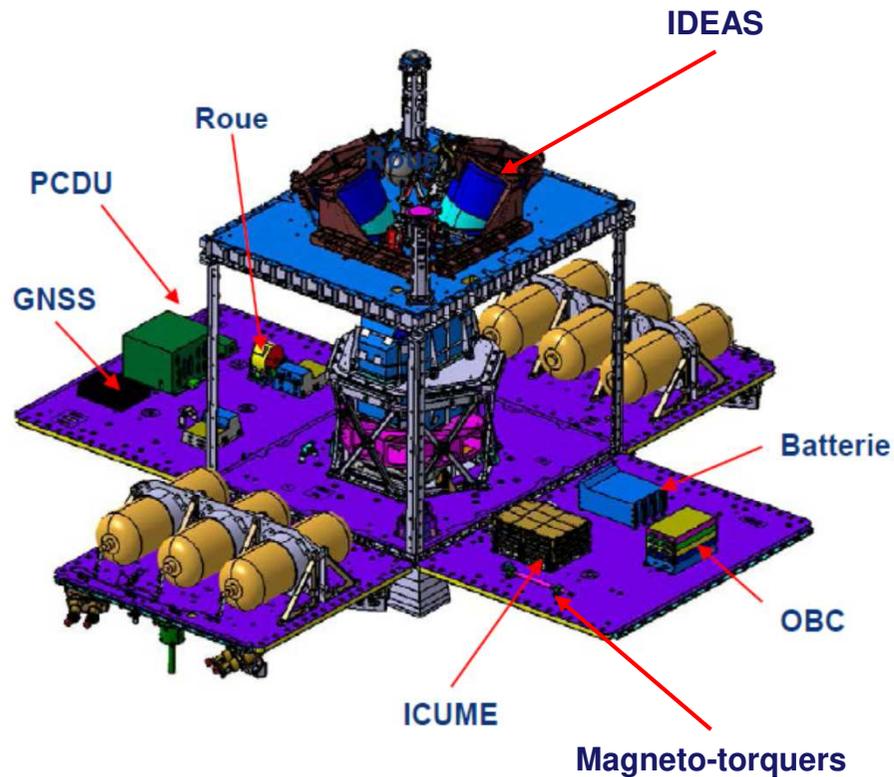


# The payload inside the satellite

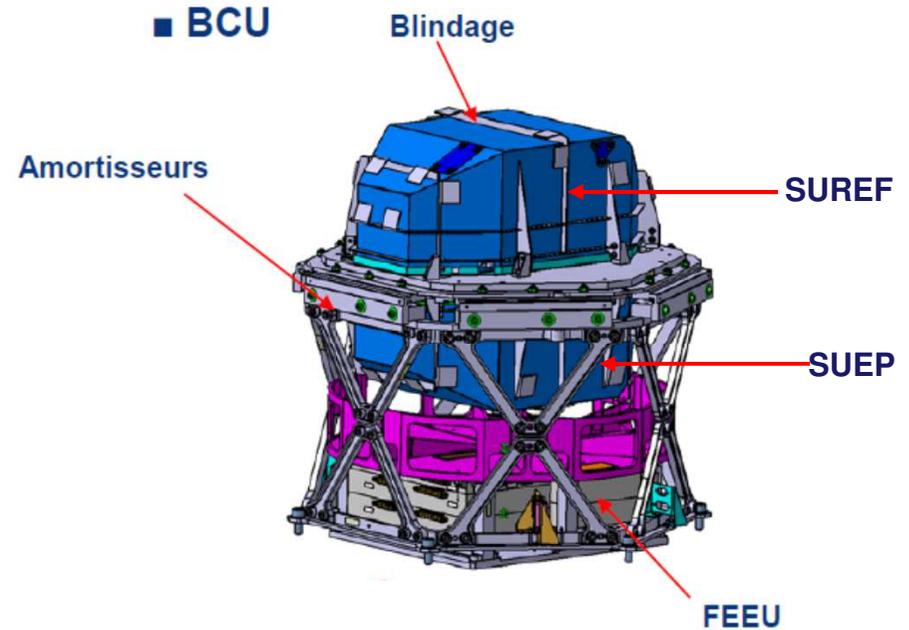


## ■ Satellite panneaux ouverts

Concept panneaux identiques Myriade

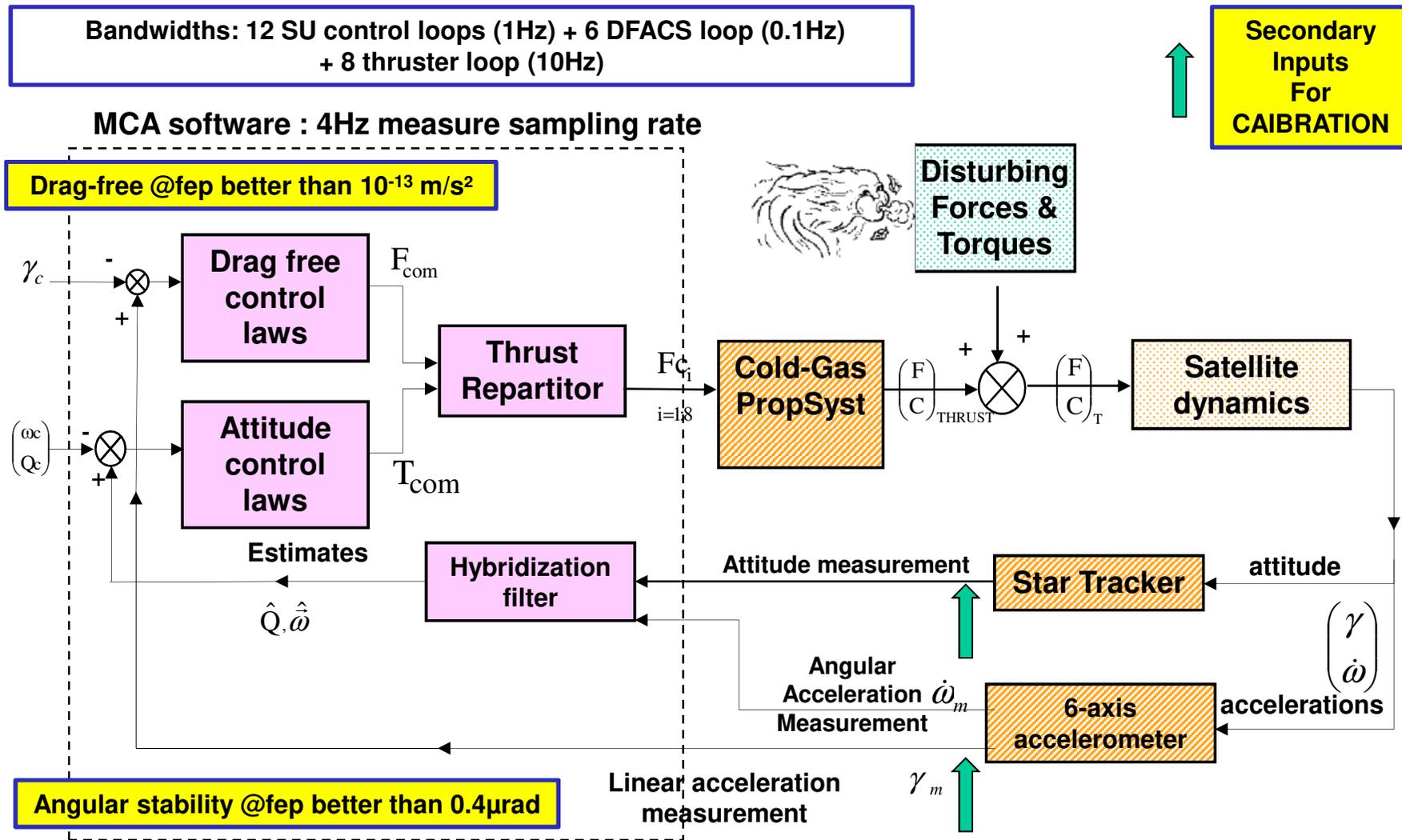


## ■ BCU

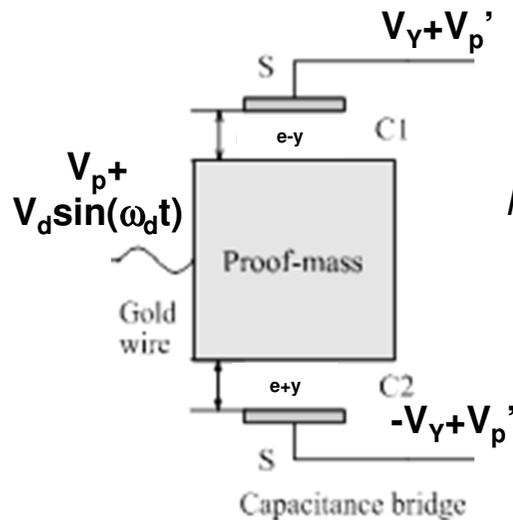


- The Sensor (SU) and the Low noise electronics (FEEU) is accommodated inside a passive thermal cocoon.
- The SU is accommodated inside a magnetic shield.

# DFACS : Drag Free & Attitude Control System of the 6 degrees of freedom



# Accelerometer principle of operation



Electrostatic force

$$F = F_1 - F_2 = \frac{1}{2} \left[ \frac{\partial C_2}{\partial y} (V_Y + V_p' - V_p - V_d \sin(\omega_d t))^2 \right] - \frac{1}{2} \left[ \frac{\partial C_1}{\partial y} (V_Y + V_p' + V_p + V_d \sin(\omega_d t))^2 \right]$$

Capacitive Detection

$$\Delta C = \frac{2\epsilon S}{e} y$$

In FRM :  $V_p \sim 40$  V and  $V_d \sim 1$  Vrms  
 In HRM :  $V_p = 5$  V and  $V_d = 5$  Vrms

THE MEASUREMENT in N0 level of data

$$a_Y = \frac{2\epsilon S}{me^3} \left( (V_p' - V_p)^2 + \frac{V_d^2}{2} \right) y - \frac{2\epsilon S}{me^2} (V_p - V_p') V_Y + \frac{2\epsilon S}{me^2} V_Y^2 \frac{y}{e}$$

Electrostatic stiffness

Electrostatic gain

Non linear term

The real observable

# Commissioning phase main events and results

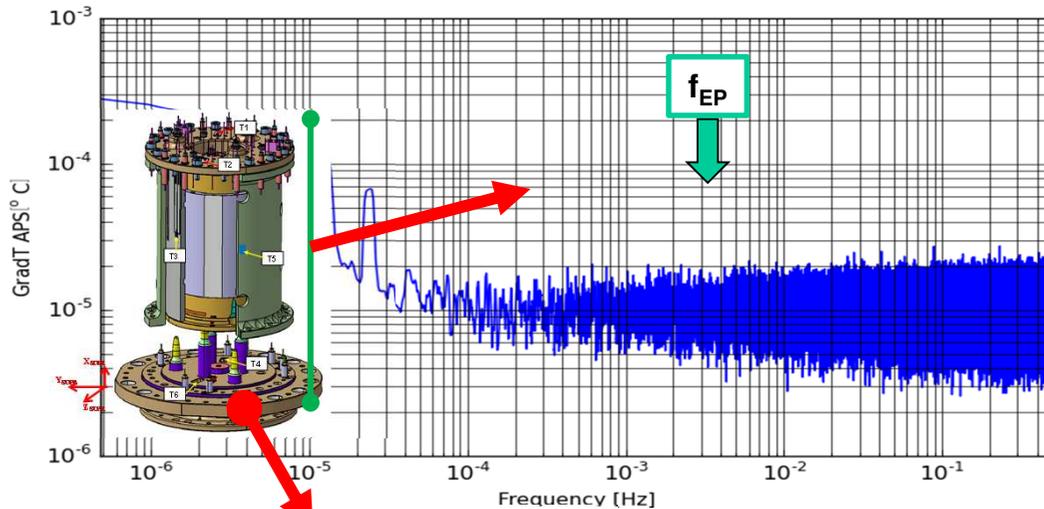


- April – Nov 2016: **hard work, rich of unexpected events**
  - Accelerometer : 2 short circuits in FEEU capacitance (SUREF). No impact on performance, still operating, with time to time need to reset the TM levitation.
  - Star sensor: some Earth's albedo light on border of images corrected by software (masks)
  - Cold Gaz thruster : minor anomalies corrected by software but bias is stable, noise  $< 0.3\mu\text{NHZ}^{-1/2}$
- **The satellite, with help of the accelerometer, of the star sensor, of the thermal passive control and of the GPS, exhibits a very quiet environment at least 10 times better than expected**
  - Star sensor:
    - DFACS Performance :  $0.03 - 0.3\mu\text{rd}$  stability @fep
    - With SU hybridization:  $0.5 - 5 \cdot 10^{-12}\text{rd/s}^2$  @fep
  - DFACS : Acceleration control over 120 orbits;  $0.3 - 4 \cdot 10^{-14}\text{m/s}^2$  @fep
  - GPS + Doppler orbit determination : 0.1-0.3 m @fep

# The commissioning phase results: Variations of Temperatures in the SU & in the FEEU



1 to 2 orders of magnitude better than specified



No signal @ 15μK level between each end of the test-masses

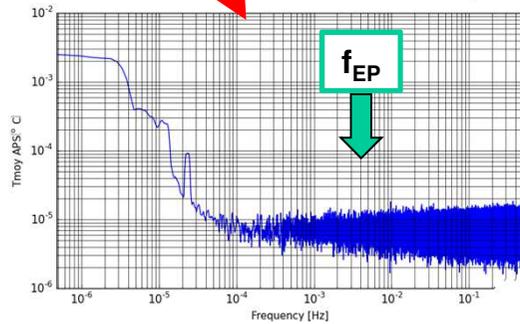
**Radiometer or radiation pressure effect**

$$\Gamma = \frac{1}{2m} PS \frac{\Delta T}{T} < 5 \cdot 10^{-16} \text{m/s}^2$$

$$\Gamma = \frac{1}{2m} S \frac{16\Delta T}{3c} \sigma T^3 < 10^{-15} \text{m/s}^2$$

No signal @ 10μK level

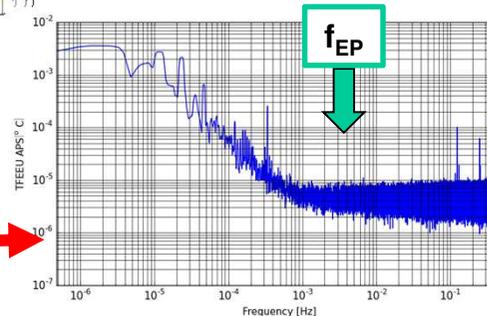
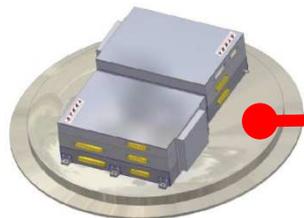
**Thermal stability of parasitic forces**  
Sensitivity tests performed on May 2017, under analysis



FFT of temperature probes

No signal @ 10μK level

**Thermal stability of electronics biases**  
Sensitivity tests performed on May 2017 => systematics of  $0.7 \cdot 10^{-15} \text{m/s}^2$



# The equation of measure



Measurement of the accelerations applied to the test masses to keep them centered and concentric

d: differential mode (half difference)  
→ contains the EP violation term

c: common mode (half sum)  
→ command of the drag-free system

EP violation parameter :

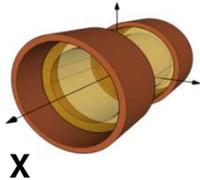
$$\delta = \frac{m_{2g}}{m_{2I}} - \frac{m_{1g}}{m_{1I}}$$

$$\Gamma_{mes,dx} = \frac{1}{2} (\Gamma_{mes,1} - \Gamma_{mes,2}) = \frac{1}{2} K_{1cx} \cdot \delta \cdot g_{x/sat} + \frac{1}{2} \begin{bmatrix} K_{1cx} \\ \eta_{cz} + \theta_{cz} \\ \eta_{cy} - \theta_{cy} \end{bmatrix}^t \cdot [T - In] \cdot \begin{bmatrix} \Delta_x \\ \Delta_y \\ \Delta_z \end{bmatrix}$$

$$\frac{1}{2} K_{1cx} \cdot \delta \cdot g_{x/sat}$$

Gravity gradient      Inertia gradient

$$\frac{1}{2} \begin{bmatrix} K_{1cx} \\ \eta_{cz} + \theta_{cz} \\ \eta_{cy} - \theta_{cy} \end{bmatrix}^t \cdot [T - In] \cdot \begin{bmatrix} \Delta_x \\ \Delta_y \\ \Delta_z \end{bmatrix}$$



$$+ \begin{bmatrix} K_{1dx} \\ \eta_{dz} + \theta_{dz} \\ \eta_{dy} - \theta_{dy} \end{bmatrix}^t \cdot (\vec{\Gamma}_{res,df} + C_x) + 2 \cdot K_{2cxx} \cdot (\Gamma_{app,dx} + b_{1dx}) \cdot (\Gamma_{res,df,x} + C_x - b_{0cx})$$

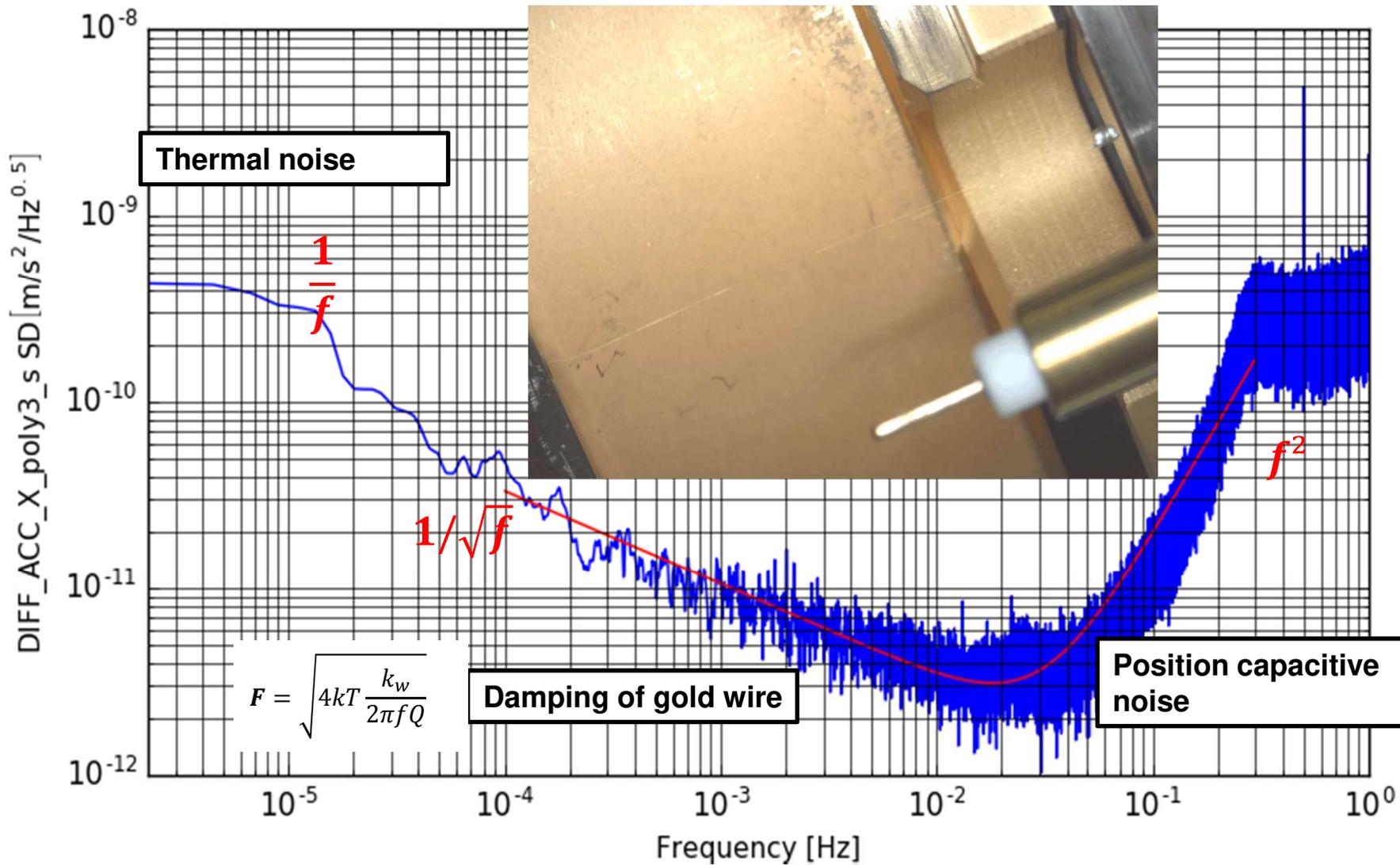
$$+ K_{2dxx} \cdot \left( (\Gamma_{res,df,x} + C_x - b_{0cx})^2 + (\Gamma_{app,dx} + b_{1dx})^2 \right)$$

$b_0$  : bias  
 $b_1$  : parasitic forces  
 $\Gamma_{res,df}$  : drag-free residual  
 $C$  : drag-free command

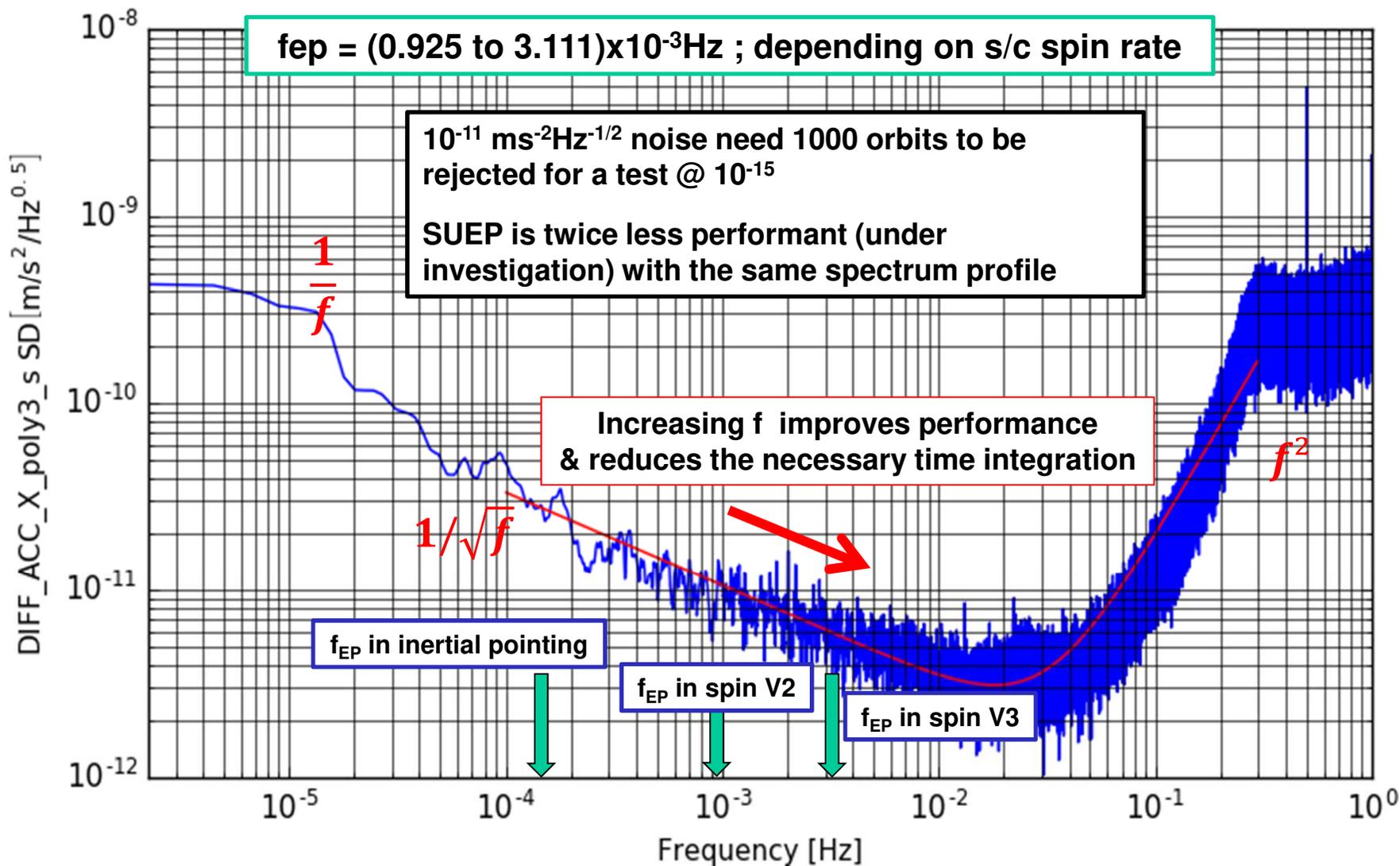
$\Delta$  : off-centering  
 $K_1$  : scale factor  
 $\eta$  : coupling

$\theta$  : misalignement  
 $K_2$  : quadratic term

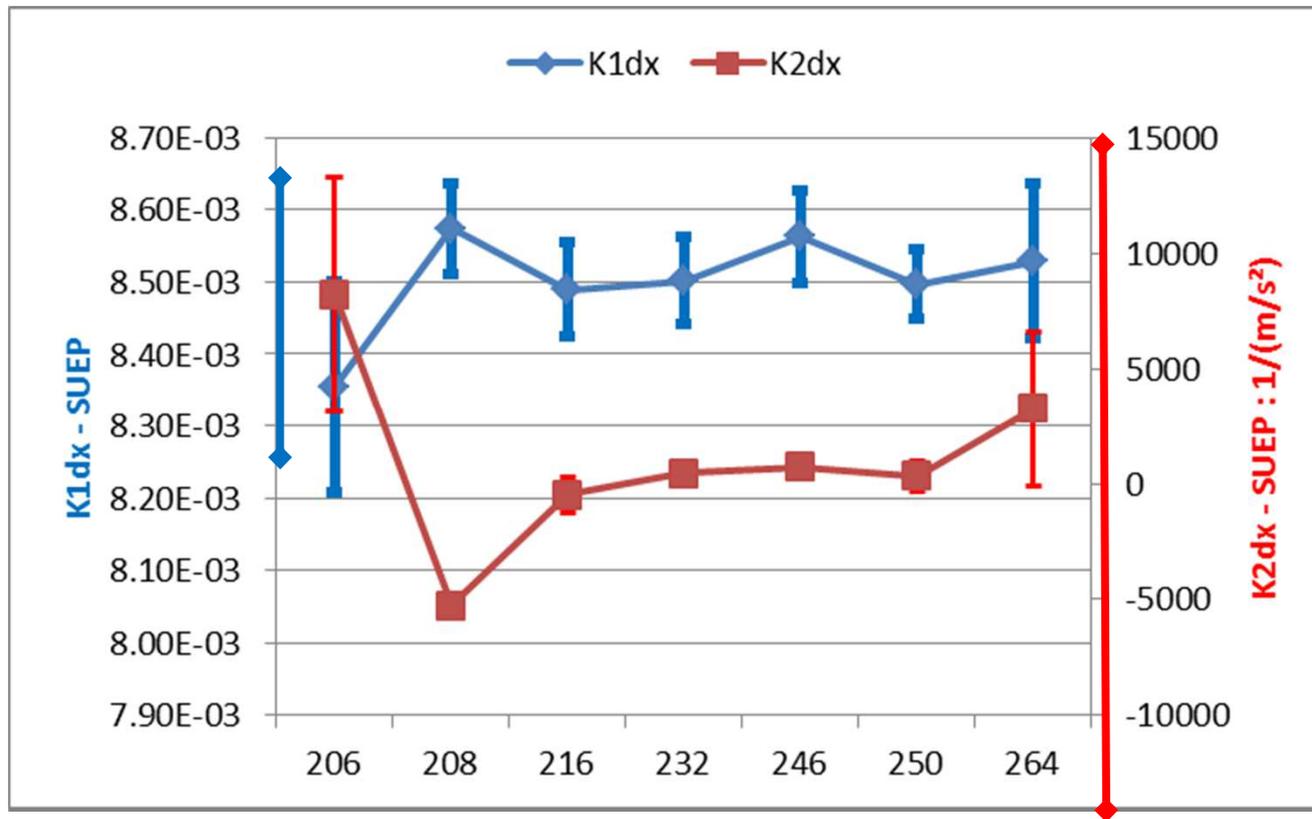
# In orbit SUREF half difference of the acceleration spectrum noise (All tone signals are subtracted from the plot)



# In orbit SUREF half difference of the acceleration spectrum noise (All tone signals are subtracted from the plot)



# Scale factor matching (K1dx) & Quadratic non linear term matching (K2dx)

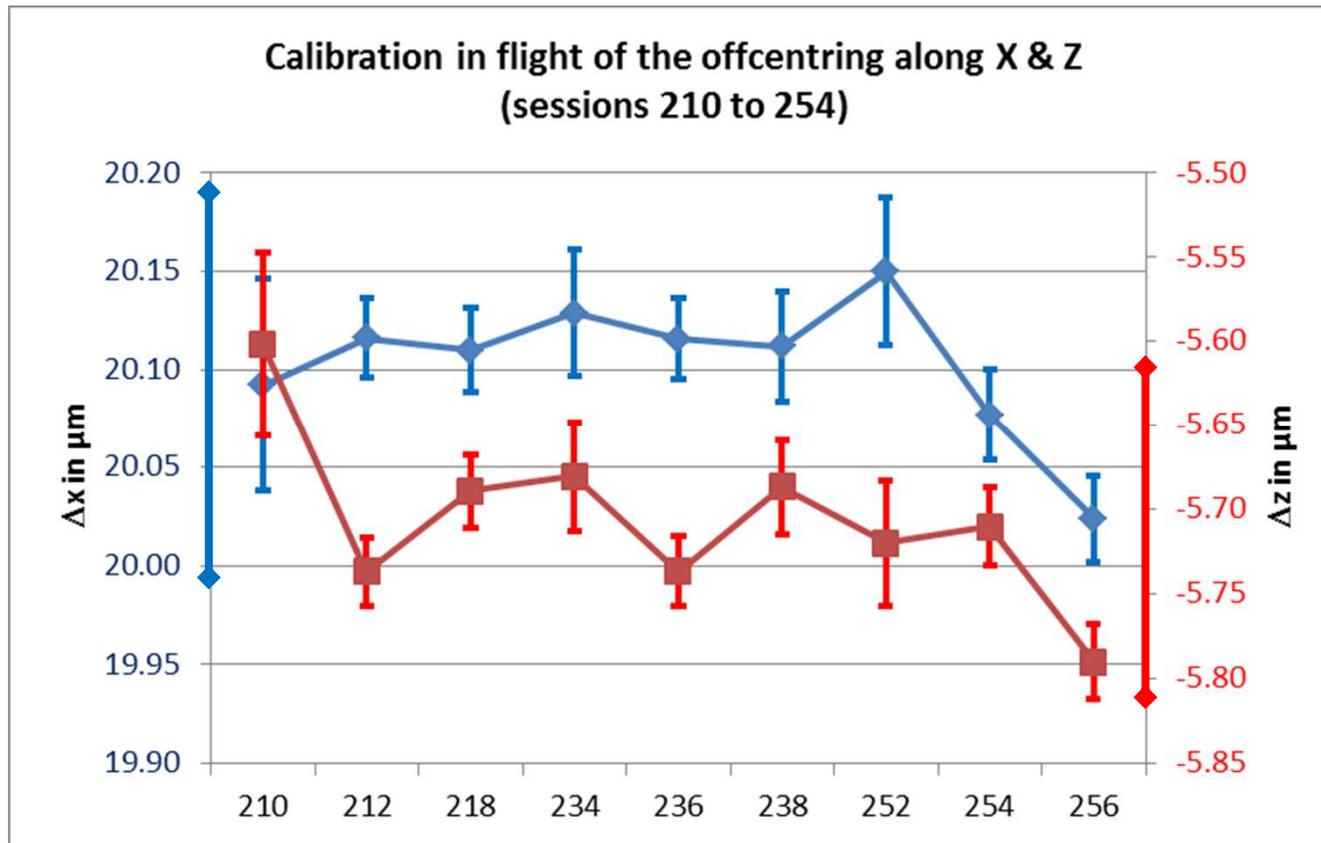


Spec domain  
on K2dx  
< 15000 (m/s<sup>2</sup>)<sup>-1</sup>

Uncertainty domain  
spec for estimation  
of K1dx  
± 2 · 10<sup>-4</sup>

- Sessions 206 & 208 have larger non-linearities (under investigations)

# Offcentring estimation from Earth's gravity gradient effect at $2 f_{EP}$



Uncertainty domain spec for estimation of  $\Delta z$   $\pm 0.1 \mu\text{m}$

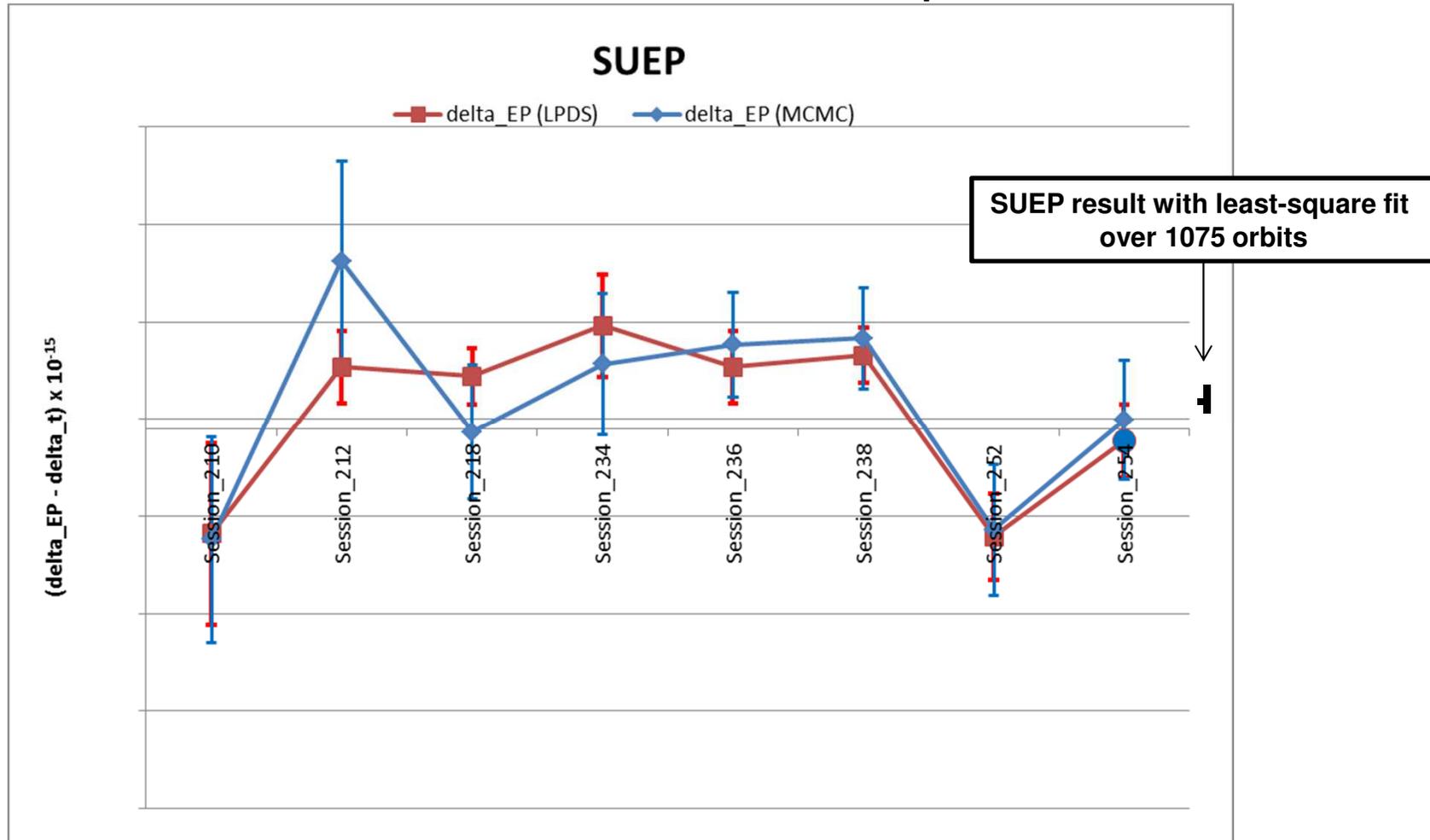
Uncertainty domain spec for estimation of  $\Delta x$   $\pm 0.1 \mu\text{m}$

- The offcentrings are extracted at the same time as the Eotvos parameter
- Dispersion on session 210 could come from non linearity at the limit of specs (session 206 & 208 performed just before)

# $\delta_{EP_i}$ with least-square fit in frequency domain & MCMC Hammer



The **scale** of Eotvos parameter is **hinted** and **biased** until publication validation (on going)  
Performed without correction of calibrated parameters



# The status of the mission scenario



<i>Orbits nb.</i>	11/05/2017	SUEP	SUREF	Total	
Technical	Commissioning Phase			829	15%
	Moon, Eclipse (TSAGE OFF)			2177	39%
	Others			609	11%
Transitions	Transitions			112	2%
Science	EP test	1205	368	1574	28%
	Calibration	196	103	300	5%

- Propulsion : 60% of the available cold gas has been consumed
- The science session will be resumed in September 2017
- With the remaining gas, we should cumulated another 480 orbits for SUEP and 424 orbits for SUREF dedicated to EP test :

=> Concerning stochastic noise, we should gain 10% in performance for SUEP and 30% for SUREF

# Science data process and preliminary results

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- 3 methods have been used and give quite the same result:
  - Monte-Carlo Markov Chains Hammer (H. Inchauspe – Post-doc ONERA)
  - Kalman Auto-Regressive Model Analysis (Q. Baghi thesis ONERA/OCA)
  - Least-square fit in the frequency domain (OCA/ONERA)
- The stochastic noise reduces with time integration and have been verified over the 1075 usable orbits
- Systematics comes principally from thermal sensitivity: at the moment an upper limit have been established and should compete the stochastic noise over 1075 orbits..... More work on going to better quantify the upper limit of the systematics

# Conclusion

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- Despite the first fears of the commissioning phase, the satellite & all subsystems are now working very well for the best detection of the Equivalence Principle ‘violation or not’ for an objective of  $10^{-15}$
- A paper is under review to give the first & preliminary scientific results on the test of EP for Pt/Ti
- The end of the mission is foreseen by mid 2018
- An announcement of distribution of data will be released after publication of the last results (2019)

## TANK YOU FOR YOUR ATTENTION

& Stay tune for very exciting results coming soon ...  
<https://microscope.onera.fr>

